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3D-POSITION TRACKING AND CONTROL FOR ALL-TERRAIN ROBOTS



Springer-Verlag Gmbh Apr 2008, 2008. Buch. Condition: Neu. Neuware - Rough terrain robotics is a fast evolving field of research and a lot of effort is deployed towards enabling a greater level of autonomy for outdoor vehicles. This book demonstrates how the accuracy of 3D position tracking can be improved by considering rover locomotion in rough terrain as a holistic problem. Although the selection of appropriate sensors is crucial to accurately track the rover's position, it is not the only...

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- Authored by Pierre Lamon
- Released at 2008



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